

## CSc 252: Computer Organization

### HW 3

due at 5pm, two days **before** the test

**Turn in through GradeScope**

# Solutions

## Policy Reminders

- You must turn in a single PDF to GradeScope. Other file formats will not be accepted. (Sorry, this is necessary for the sanity of the TAs!)
- You are allowed to work with other students on this homework, as we will not be grading it for correctness. However, **each student must turn in their own copy of the homework.**
- **Show your work for all problems.** While we won't be grading for correctness, you will not receive full credit unless you show your work.

After all, showing your work is required on the test - and homeworks are intended to help you practice for the test!

## Required Problems:

3.1(d), 3.2(d), 3.3(d), 3.4(d)

## Allowable Instructions

When writing MIPS assembly, the only instructions that you are allowed to use (so far) are:

- add, addi, sub, addu, addiu, subu
- beq, bne, j, jal, jr
- slt, slti
- and, andi, or, ori, nor, nori, xor, xori
- sll, srl, sra
- lw, lh, lb, sw, sh, sb
- la
- syscall

While MIPS has many other useful instructions (and the assembler recognizes many pseudo-instructions), do not use them! We want you to learn the **fundamentals** of how assembly language works - you can use fancy tricks after this class is over.

## Problem 3.1 - ALUs

In this problem, you will simulate an ALU, following the designs we've seen in class. However, to make the work easier, you will only need to simulate a 4-bit ALU, not a 32-bit one. (Just like in the 32-bit ALU, the Less input for ALU Element 0 - the LSB - comes from the adder output from ALU Element 3 - the MSB.)

### 3.1(a)

Give the proper control bits - that is, the `bNegate` and `aluOp` values - to configure the ALU to Add. Then, consider what would happen if the input values were as follows:

a = 1101  
b = 0111

Give the following values as 4 bit numbers:

- The 4 AND bits
- The 4 OR bits
- The 4 Add results
- The 4 Out values (that is, the output from the various Result MUXes)

### 3.1(b)

Repeat part (a), except that you must give the configuration to perform subtraction. This time, give the following information:

- The 4 Add results
- The 4 Less inputs
- The 4 Out values (that is, the output from the various Result MUXes)

For this problem, use the following input values:

a = 0011  
b = 1001

### 3.1(c)

Repeat part (b), except that you must give the configuration bits to perform Set-Less-Than. Report the same output information as from part(b).

For this problem, use the following input values:

a = 1111  
b = 0110

### 3.1(d) - Turn in this one

Repeat part (a), except that you must give the configuration to perform OR.

For this problem, use the following input values:

a = 0100

b = 1001

**Solution:** For OR, we must set `bNegate==0` and `aluOp==1`.

The AND bits are: 0000

The OR bits are: 1101

The Add results are : 1101

Since `aluOp==1` we will select the OR result in every ALU Element as our the desired Output. Therefore, the output will be 1101

## Problem 3.2 - Tracking a Stack

### 3.2(a)

In this problem, `foo()` calls `bar()`. The first column shows the state of the stack while `foo()` is running, just before its startup code.

In the second column, show the state of the stack after the startup code in `foo()` has completed, but before the `jal` instruction. In the third column show the state of the stack after `bar()` has run its function prologue **and** it has saved any registers that are required.

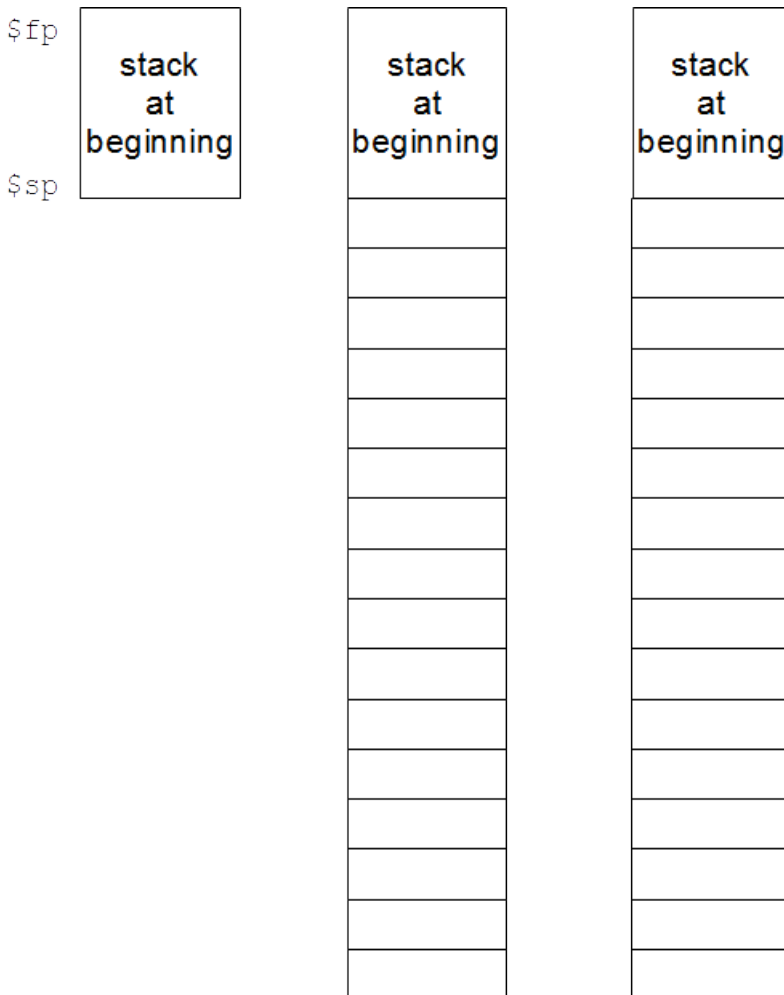
**Make sure to mark:**

- The positions of `$fp`, `$sp`
- All values which have been written to stack

Use `arg1`, `arg2`, etc. for the various parameters. Use `arg1` for the first parameter - which is stored in `$a0`.

**Notes:**

- When this problem begins, `foo()` is using (and wants to preserve) the registers `$t0`, `$t1`, `$t2`, `$s3`, `$s4`, `$s5`.
- `bar()` takes 5 parameters. It will need to the 1st, 3rd, and 5th on the stack.
- `bar()` will be using the following registers somewhere in its code: `$s0`, `$s1`, `$t2`, `$t3`, `$t4`.



### 3.2(b)

In this problem, `foo()` calls `bar()`. The first column shows the state of the stack while `foo()` is running, just before its startup code.

In the second column, show the state of the stack after the startup code in `foo()` has completed, but before the `jal` instruction. In the third column show the state of the stack after `bar()` has run its function prologue, but before it saved any other than the prologue (not even `aX` registers). In the third column show the state of the stack after `bar()` has saved all necessary registers.

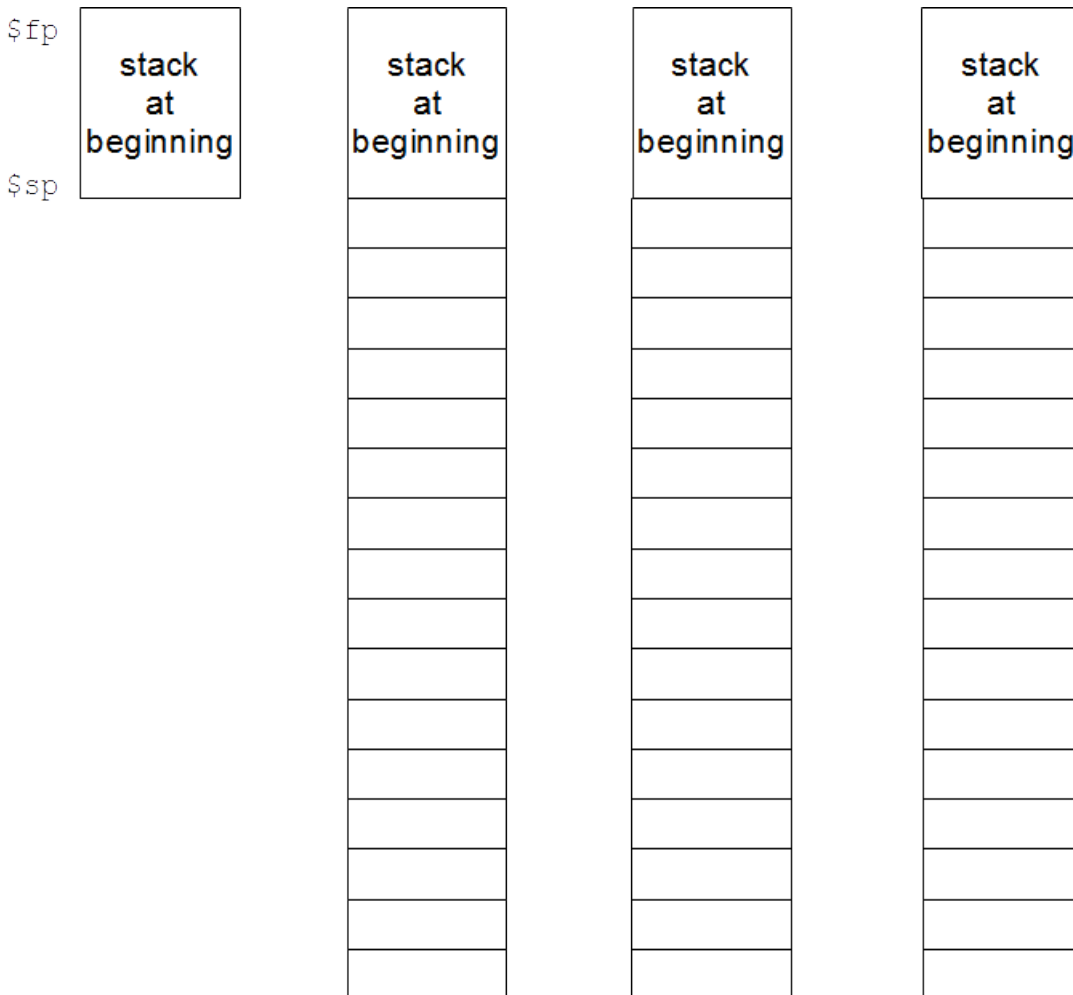
**Make sure to mark:**

- The positions of `$fp`, `$sp`
- All values which have been written to stack

Use `arg1`, `arg2`, etc. for the various parameters. Use `arg1` for the first parameter - which is stored in `$a0`.

**Notes:**

- When this problem begins, `foo()` is using (and wants to preserve) the registers `$s3`, `$s4`, `$t0`, `$t6`, `$t7`.
- `bar()` takes 2 parameters. It will need to store both on the stack.
- `bar()` will be using the following registers somewhere in its code: `$s3`, `$s4`, `$t0`, `$t1`.



### 3.2(c)

In this problem, `foo()` calls `bar()`. The first column shows the state of the stack while `foo()` is running, just before its startup code.

In the second column, show the state of the stack after the startup code in `foo()` has completed, but before the `jal` instruction. In the third column show the state of the stack after `bar()` has run its function prologue, but before it saved any other than the prologue (not even `aX` registers). In the fourth column show the state of the stack after `bar()` has saved all necessary registers.

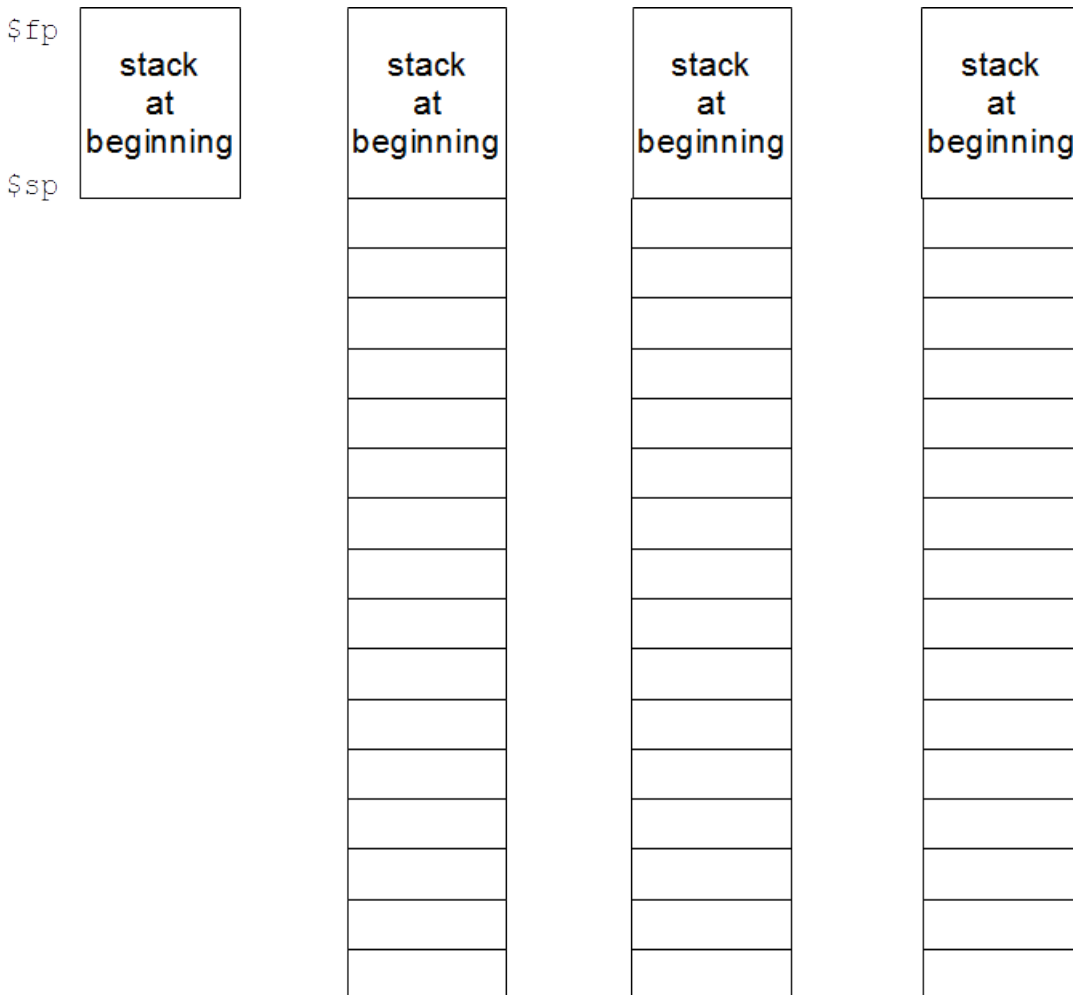
**Make sure to mark:**

- The positions of `$fp`, `$sp`
- All values which have been written to stack

Use `arg1`, `arg2`, etc. for the various parameters. Use `arg1` for the first parameter - which is stored in `$a0`.

**Notes:**

- When this problem begins, `foo()` is using (and wants to preserve) the registers `$t2`, `$s0`, `$s1`, `$s2`, `$s3`.
- `bar()` takes 8 parameters. It will need to store the first and fourth on the stack.
- `bar()` will be using the following registers somewhere in its code: `$t0`, `$t1`, `$t3`, `$t4`, `$s4`, `$s5`, `$s6`, `$s7`.



### 3.2(d) - Turn in this one

In this problem, `foo()` calls `bar()`. The first column shows the state of the stack while `foo()` is running, just before its startup code.

In the second column, show the state of the stack after the startup code in `foo()` has completed, but before the `jal` instruction. In the third column show the state of the stack after `bar()` has run its function prologue, but before it saved any other than the prologue (not even `aX` registers). In the fourth column show the state of the stack after `bar()` has saved all necessary registers.

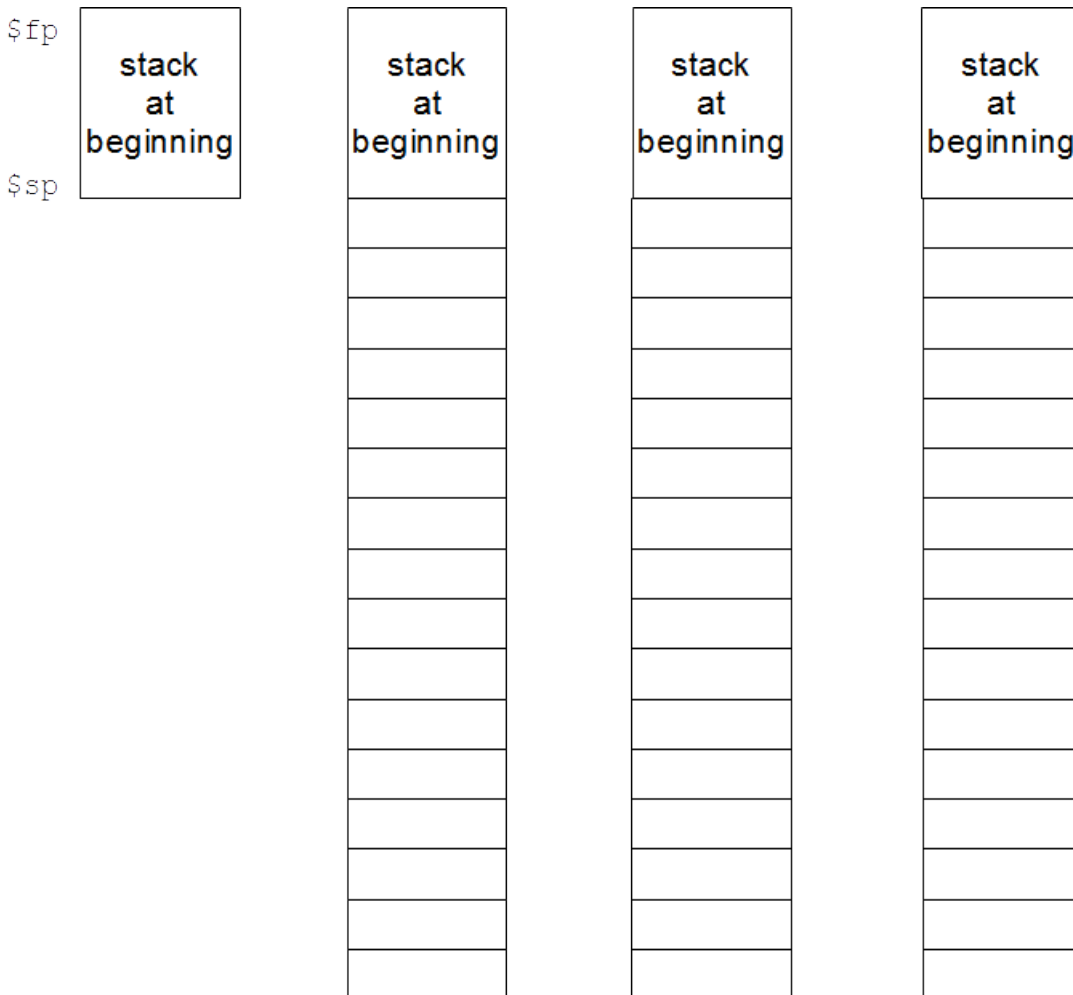
**Make sure to mark:**

- The positions of `$fp`, `$sp`
- All values which have been written to stack

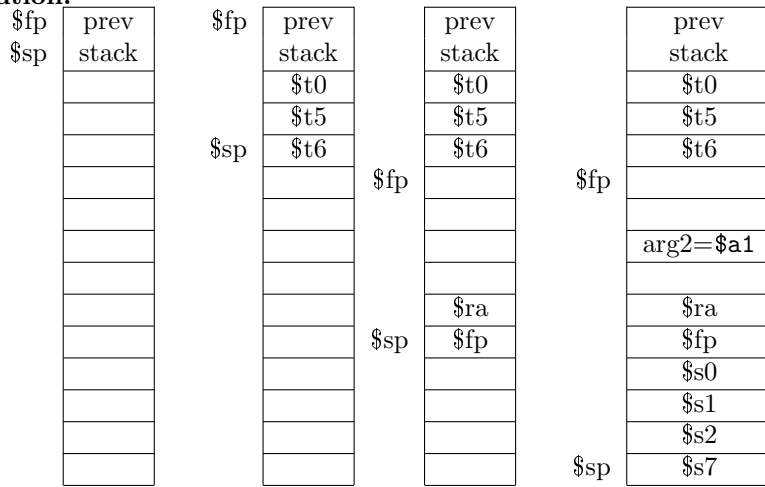
Use `arg1`, `arg2`, etc. for the various parameters. Use `arg1` for the first parameter - which is stored in `$a0`.

**Notes:**

- When this problem begins, `foo()` is using (and wants to preserve) the registers `$t0`, `$t5`, `$t6`, `$s0`, `$s2`, `$s5`, `$s6`.
- `bar()` takes 2 parameters. It will need to store the second on the stack.
- `bar()` will be using the following registers somewhere in its code: `$t1`, `$t2`, `$t3`, `$t4`, `$t5`, `$t6`, `$s0`, `$s1`, `$s2`, `$s7`.



**Solution:**



## Problem 3.3 - Calling Functions

For each problem below, I have given a set of registers which are currently in use and which need to be saved, and then a function call with a certain set of parameters. Write the code that should run in the **caller** - including the startup and cleanup code. Save every register which might be destroyed by the called function, but do **not** save any register which would be saved by the called function.

### 3.3(a)

Registers to save: \$s0, \$s1, \$s3, \$t0, \$t1, \$t2  
Call to make: foo(1,2)

### 3.3(b)

Registers to save: \$s2, \$s4, \$s6, \$t1, \$t3, \$t5  
Call to make: bar(0, 0x1234, str)  
(Assume that str is a label of a string. Pass the **address** of the first character as the third parameter.)

### 3.3(c)

Registers to save: \$t1, \$t2, \$t3, \$t4, \$s0, \$s1  
Call to make: fred(123, 456, 0xabc, 0xdef, 0, 10)

### 3.3(d) - Turn in this one

Registers to save: \$t0, \$t1, \$s1, \$s3, \$s5, \$s7  
Call to make: qwerty('a', 10, 'B', -2, 0xffff)

#### Solution:

```
addiu $sp, $sp, -8
sw    $t0, 4($sp)
sw    $t1, 0($sp)

addi  $a0, $zero, 'a'      # 'a' is the same as 97
addi  $a1, $zero, 10
addi  $a2, $zero, 'B'     # 'B' is the same as 66
addi  $a3, $zero, -2

# we don't want to save t5, so it's OK to use it as a
# temporary in this code.
ori   $t5, $zero, 0xffff  # t5 = 0xffff
sw    $t5, -4($sp)       # arg5 = 0xffff

jal   qwerty

lw    $t1, 0($sp)
lw    $t0, 4($sp)
addiu $sp, $sp, 8
```

## Problem 3.4 - Function Prologues and Epilogues

For each problem below, I have given a set of registers which will be modified by a certain function, along with the number of parameters it has; I will also list if any of the parameters need to be copied to the stack (so that they can be saved across a future function call). Write the appropriate prologue and epilogue **plus** the register save/restore code) for this function.

### 3.4(a)

Registers which will be modified: \$s0, \$s1, \$s3, \$t0, \$t1, \$t2

Number of Parameters: 3

Parameters to Save on Stack: \$a2

### 3.4(b)

Registers which will be modified: \$s2, \$s4, \$s6, \$t1, \$t3, \$t5

Number of Parameters: 3

Parameters to Save on Stack: None

### 3.4(c)

Registers which will be modified: \$t1, \$t2, \$t3, \$t4, \$s0, \$s1

Number of Parameters: 6

Parameters to Save on Stack: \$a0, \$a1, \$a2, \$a3

### 3.4(d) - Turn in this one

Registers which will be modified: \$t2, \$t3, \$t4, \$t5, \$t6, \$s1

Number of Parameters: 5

Parameter(s) to Save on Stack: \$a1

<b>Solution:</b>
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```
addiu $sp, $sp, -28
sw    $ra, 4($sp)
sw    $fp, 0($sp)
addiu $fp, $sp, 24

# save the aX registers
sw    $a1, 12($sp)

# save the sX registers that we're going to use.
addiu $sp, $sp, -4
sw    $s1, 0($sp)

... body ...

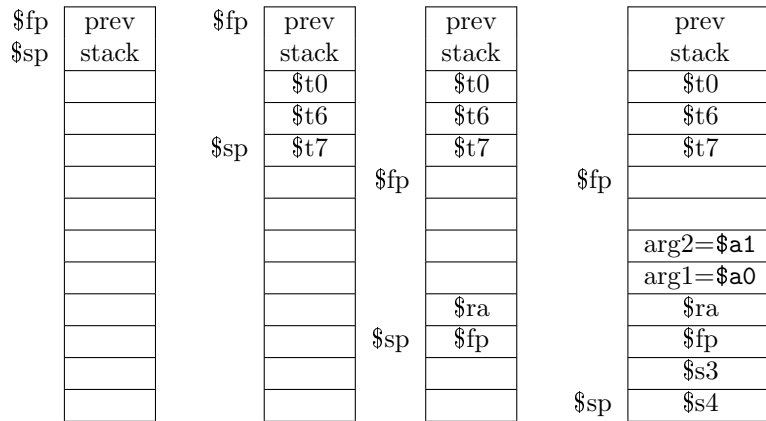
lw    $s1, 0($sp)
addiu $sp, $sp, 4

lw    $fp, 0($sp)
lw    $ra, 4($sp)
addiu $sp, $sp, 28
jr    $ra
```

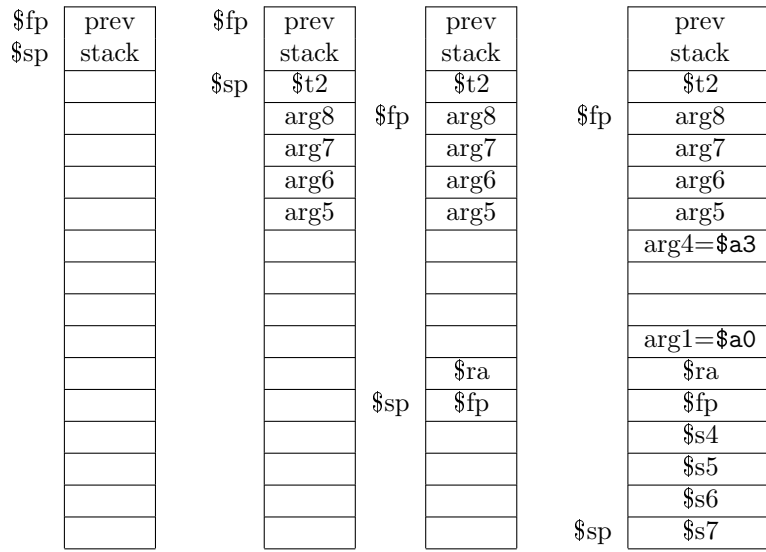
# EXAMPLES



**Example: Problem 3.2(b)**



**Example: Problem 3.2(c)**



### Example: Problem 3.3(a)

```
addiu $sp, $sp, -12
sw    $t0, 8($sp)
sw    $t1, 4($sp)
sw    $t2, 0($sp)

addi  $a0, $zero, 1
addi  $a1, $zero, 2

jal   foo

lw    $t2, 0($sp)
lw    $t1, 4($sp)
lw    $t0, 8($sp)
addiu $sp, $sp, 12
```

### Example: Problem 3.3(b)

```
addiu $sp, $sp, -12
sw    $t1, 8($sp)
sw    $t3, 4($sp)
sw    $t5, 0($sp)

addi  $a0, $zero, 0
addi  $a1, $zero, 0x1234
la    $a2, str

jal   bar

lw    $t5, 0($sp)
lw    $t3, 4($sp)
lw    $t1, 8($sp)
addiu $sp, $sp, 12
```

### Example: Problem 3.3(c)

```
addiu $sp, $sp, -16
sw    $t1, 12($sp)
sw    $t2, 8($sp)
sw    $t3, 4($sp)
sw    $t4, 0($sp)

addi  $a0, $zero, 123
addi  $a1, $zero, 456
addi  $a2, $zero, 0xabc
addi  $a3, $zero, 0xdef

# we don't want to save t5, so it's OK to use it as a
# temporary in this code.
sw    $zero, -8($sp)      # arg5 = 0
addi  $t5, $zero, 10
sw    $t5, -4($sp)       # arg6 = 10

jal   fred

lw    $t4, 0($sp)
lw    $t3, 4($sp)
lw    $t2, 8($sp)
lw    $t1, 12($sp)
addiu $sp, $sp, 16
```

### Example: Problem 3.4(a)

```
addiu $sp, $sp, -24
sw    $ra, 4($sp)
sw    $fp, 0($sp)
addiu $fp, $sp, 20

sw    $a2, 16($sp)

addiu $sp, $sp, -12
sw    $s0, 8($sp)
sw    $s1, 4($sp)
sw    $s3, 0($sp)

... body ...

lw    $s3, 0($sp)
lw    $s1, 4($sp)
lw    $s0, 8($sp)
addiu $sp, $sp, 12

lw    $fp, 0($sp)
lw    $ra, 4($sp)
addiu $sp, $sp, 24
jr    $ra
```

### Example: Problem 3.4(b)

```
addiu $sp, $sp, -24
sw    $ra, 4($sp)
sw    $fp, 0($sp)
addiu $fp, $sp, 20
```

```
addiu $sp, $sp, -12
sw    $s2, 8($sp)
sw    $s4, 4($sp)
sw    $s6, 0($sp)
```

... body ...

```
lw    $s6, 0($sp)
lw    $s4, 4($sp)
lw    $s2, 8($sp)
addiu $sp, $sp, 12
```

```
lw    $fp, 0($sp)
lw    $ra, 4($sp)
addiu $sp, $sp, 24
jr    $ra
```

### Example: Problem 3.4(c)

```
addiu $sp, $sp, -32
sw    $ra, 4($sp)
sw    $fp, 0($sp)
addiu $fp, $sp, 28

# save the aX registers
sw    $a0, 8($sp)
sw    $a1, 12($sp)
sw    $a2, 16($sp)
sw    $a3, 20($sp)

# save the sX registers that we're going to use.
addiu $sp, $sp, -8
sw    $s0, 4($sp)
sw    $s1, 0($sp)

... body ...

lw    $s1, 0($sp)
lw    $s0, 4($sp)
addiu $sp, $sp, 8

lw    $fp, 0($sp)
lw    $ra, 4($sp)
addiu $sp, $sp, 32
jr    $ra
```